

VECTORS IN TWO DIMENSIONS

scalar quantity	scalar	directed line segment
initial point	terminal point	magnitude
equivalent vectors	equal vectors	velocity vector
force vector	displacement	sum of vectors
resultant force	scalar multiple	position vector
components of vector	$\mathbf{a} = (a_1, a_2)$	

Notation: \mathbb{R}^2 is the set of all vectors (x, y) where x and y are real numbers.

Definition: The **magnitude** $\|\mathbf{a}\|$ of the vector $\mathbf{a} = (a_1, a_2)$ is $\|\mathbf{a}\| = \sqrt{a_1^2 + a_2^2}$

Definition: (Addition of Vectors): $(a_1, a_2) + (b_1, b_2) = (a_1 + b_1, a_2 + b_2)$

Definition: (Scalar Multiple of a Vector): $c (a_1, a_2) = (ca_1, ca_2)$

Definition: The **zero vector** $\mathbf{0}$ is $\mathbf{0} = (0, 0)$,
and the **negative of a** is $-\mathbf{a} = - (a_1, a_2) = (-a_1, -a_2)$

Theorem: The follow properties hold for vectors $\mathbf{a}, \mathbf{b}, \mathbf{w}$ and all scalars c and d :

$\mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a}$	$\mathbf{a} + (\mathbf{b} + \mathbf{w}) = (\mathbf{a} + \mathbf{b}) + \mathbf{w}$	$\mathbf{a} + \mathbf{0} = \mathbf{a}$
$\mathbf{a} + (-\mathbf{a}) = \mathbf{0}$	$c(\mathbf{a} + \mathbf{b}) = c\mathbf{a} + c\mathbf{b}$	$(c+d)\mathbf{a} = c\mathbf{a} + d\mathbf{a}$
$(cd)\mathbf{a} = c(d\mathbf{a}) = d(c\mathbf{a})$	$1\mathbf{a} = \mathbf{a}$	$0\mathbf{a} = \mathbf{0} = c\mathbf{0}$

Definition: If $\mathbf{a} = (a_1, a_2)$ and $\mathbf{b} = (b_1, b_2)$, the **difference** $\mathbf{a} - \mathbf{b}$ is $\mathbf{a} + (-\mathbf{b})$.

Theorem: If $P_1(x_1, y_1)$ and $P_2(x_2, y_2)$ are any two points, then the vector \mathbf{a} in \mathbb{R}^2 that corresponds to P_1P_2 is $\mathbf{a} = (x_2 - x_1, y_2 - y_1)$.

Definition: Nonzero vectors \mathbf{a} and \mathbf{b} in \mathbb{R}^2 have

- (i) the **same direction** if $\mathbf{b} = c\mathbf{a}$ for some positive scalar $c > 0$.
 - (ii) the **opposite direction** if $\mathbf{b} = c\mathbf{a}$ for some negative scalar $c < 0$.
- The vectors \mathbf{a} and \mathbf{b} are **parallel** if $\mathbf{b} = c\mathbf{a}$ for some scalar c

Theorem: If \mathbf{a} is a vector and c is a scalar, then $\|c\mathbf{a}\| = |c| \|\mathbf{a}\|$

Definition: $\mathbf{i} = (1, 0), \mathbf{j} = (0, 1)$

Theorem: If $\mathbf{a} = (a_1, a_2)$, then $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j}$

Definition: If $\mathbf{a} = (a_1, a_2)$, then a_1 is the **horizontal component** of \mathbf{a} and a_2 is the **vertical component** of \mathbf{a} .

VECTORS IN THREE DIMENSIONS

ordered triple	xy-plane	x- coordinate
equality of triples	yz-plane	y- coordinate
origin	xz-plane	z-coordinate
right-handed coordinate system	rectangular coordinate system	xyz-coordinate system

Distance Formula: The distance between $P_1(x_1, y_1, z_1)$ and $P_2(x_2, y_2, z_2)$ is

$$d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Midpoint Formula: The midpoint of the line segment from $P_1(x_1, y_1, z_1)$ to $P_2(x_2, y_2, z_2)$ is

$$\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2} \right)$$

Definition: The **graph of an equation** in three variables x , y , and z is the set of all points $P(a, b, c)$ in a rectangular coordinate system such that the ordered triple (a, b, c) is a solution of the equation. The graph of such an equation is called a **surface**.

Theorem: An equation of a sphere of radius r and center $P_0(x_0, y_0, z_0)$ is

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$$

Definition: \mathbb{R}^3 is the set of all vectors (x, y, z) where x , y and z are real numbers.

Definition: In \mathbb{R}^3 , $\mathbf{i} = (1, 0, 0)$, $\mathbf{j} = (0, 1, 0)$, and $\mathbf{k} = (0, 0, 1)$.

Note: We may write the vector $\mathbf{a} = (a_1, a_2, a_3)$ as $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$