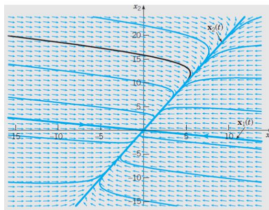


MATH 226: Differential Equations

Nodal Sources and Nodal Sinks



The pattern of trajectories in Figure is typical of all second order systems $\mathbf{x}' = \mathbf{A}\mathbf{x}$ whose eigenvalues are real, different, and of the same sign. The origin is called a **node** for such a system.

Class 15: March 14, 2025





Notes on Assignment 8
Assignment 9

In Handouts Folder:

PhasePlane Tutorial (also need PlotPhasePlane.m)

Announcements

For Next Time, Work Through

Complex Numbers

- Use the imaginary unit i to write complex numbers, and add, subtract, and multiply complex numbers.
- Find complex solutions of quadratic equations.
- Write the trigonometric forms of complex numbers.
- Find powers and n th roots of complex numbers.

Our Main Agenda

Solve $\mathbf{X}' = \mathbf{A} \mathbf{X}$ where $\mathbf{A}$ is an $n \times n$ matrix of constants and $\mathbf{X}$ is an n -dimensional vector of functions.

Results So Far

Theorem: The set of solutions is an n -dimensional vector space.

We can find some solutions of the form $e^{\lambda t} \vec{v}$ where λ is an eigenvalue of $\mathbf{A}$ and $\vec{v}$ is an associated eigenvector.

Distinct eigenvalues give rise to linearly independent solutions.

Outstanding Questions

How to handle complex eigenvalues.

How to find n linearly independent solutions to $\mathbf{X}' = \mathbf{A} \mathbf{X}$ when there are not enough of the form $e^{\lambda t} \vec{v}$.

Comments on Some Homework Problems

Section 3.1 : Exercise 38

Show that $\lambda = 0$ is an eigenvalue for a matrix **A**
if and only if
 $\det(\mathbf{A}) = 0$.

Must Prove Both:

- ▶ If $\lambda = 0$ is an eigenvalue, then $\det(\mathbf{A}) = 0$, **AND**
- ▶ If $\det(\mathbf{A}) = 0$, then $\lambda = 0$ is an eigenvalue of **A**.

If $\lambda = 0$ is an eigenvalue, then $\det(\mathbf{A}) = 0$

Proof:

If $\lambda = 0$ is an eigenvalue, then there is a nonzero vector $\vec{v}$ such that $\mathbf{A} \vec{v} = \vec{0}$.

Hence $\mathbf{A}$ is not invertible so $\det(\mathbf{A}) = 0$.

If $\det(\mathbf{A}) = 0$, then $\lambda = 0$ is an eigenvalue of $\mathbf{A}$.

Proof: Note that $\mathbf{A} = \mathbf{A} - \mathbf{0} = \mathbf{A} - 0 \mathbf{I}$.

If $\det(\mathbf{A}) = 0$, then $\det(\mathbf{A} - 0 \mathbf{I}) = 0$

so 0 satisfies the characteristic equation for $\mathbf{A}$ and hence is an eigenvalue.

Comments on Some Homework Problems

Section 3.2 Exercise 30c

Use a computer to draw component plots of the initial value problem and the equilibrium solutions.

See Problem 30 on Page 144.maple

Current Goal:
**Continue Study of Linear
Homogeneous Systems
With Constant Coefficients**

$$X' = A X$$

2×2 Case

Theorem: If λ and μ are distinct eigenvalues (real or complex) of a 2×2 matrix A having corresponding eigenvectors $\vec{v}$ and $\vec{w}$, then every solution of $\mathbf{x}' = A \mathbf{x}$ is a linear combination of $e^{\lambda t} \vec{v}$ and $e^{\mu t} \vec{w}$.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Characteristic Polynomial of A is $\det(A - \lambda I) =$
 $\lambda^2 - (a + d)\lambda + ad - bc$
 $\lambda^2 - \text{Trace}(A) \lambda + \text{Det } A$

Characteristic Equation: $\det(A - \lambda I) = 0$

Eigenvalues Are Roots of Characteristic Polynomial

$$\lambda = \frac{(a + d) \pm \sqrt{(a + d)^2 - 4(ad - bc)}}{2}$$

$$\lambda = \frac{(a + d) \pm \sqrt{(a - d)^2 + 4bc}}{2}$$

$$\lambda = \frac{(a + d) \pm \sqrt{(a - d)^2 + 4bc}}{2}$$

Possibilities

2 Real Unequal Roots

2 Complex Roots

1 Real Double Root

More About 2 Real Unequal Roots Case

$$\mathbf{x}' = A \mathbf{x}$$

The Origin (0,0) is an equilibrium and is called a **NODE**

More About 2 Real Unequal Roots Case $\mathbf{x}' = A \mathbf{x}$

The Origin (0,0) is an equilibrium and is called a **NODE**

$\lambda_1, \lambda_2 < 0$ Node is Asymptotically Stable
NODAL SINK

$\lambda_1, \lambda_2 > 0$ Node is Unstable
NODAL SOURCE

Opposite Sign Node is Unstable
SADDLE POINT

Nodal Sink $\begin{bmatrix} -7 & 3 \\ 2 & -2 \end{bmatrix}$ $\lambda = -1, -8$

Nodal Source $\begin{bmatrix} 2 & 0 \\ -1 & 3 \end{bmatrix}$ $\lambda = 3, 2$

Saddle Point $\begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix}$ $\lambda = 3, -1$

ZERO AS AN EIGENVALUE

Example: Richardson Arms Race Model

With Parallel Stable Lines

$$x' = -mx + ay + r$$

$$y' = bx - ny + s$$

$$\text{Slope of } \mathbf{L} = \frac{m}{a}$$

$$\text{Slope of } \mathbf{L}' = \frac{b}{n}$$

$$\text{Parallel if } \frac{m}{a} = \frac{b}{n}$$

$$A = \begin{bmatrix} -m & a \\ b & -n \end{bmatrix}$$

$$mn = ab \Leftrightarrow mn - ab = 0 \Leftrightarrow \det(A) = 0$$

$$\text{Characteristic Equation: } \lambda^2 + (m+n)\lambda + (mn - ab) = 0$$

$$\lambda^2 + (m+n)\lambda = 0$$

$$\lambda(\lambda + (m+n)) = 0 \Rightarrow \lambda = 0, \lambda = -(m+n)$$

ZERO AS AN EIGENVALUE EXAMPLE

$$m = 3, a = 6, n = 8, b = 4$$

$$A = \begin{bmatrix} -3 & 6 \\ 4 & -8 \end{bmatrix}$$

$$\det \begin{bmatrix} -3 - \lambda & 6 \\ 4 & -8 - \lambda \end{bmatrix}$$

$$= (-3 - \lambda)(-8 - \lambda) - 24 = \lambda^2 + 11\lambda + 24 - 24$$

$$= \lambda^2 + 11\lambda = \lambda(\lambda + 11)$$

$$\lambda = 0, \lambda = -11$$

For $\lambda = -11$:

$$\begin{bmatrix} 8 & 6 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$4v_1 + 3v_2 = 0$$

$$\vec{v} = \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

For $\lambda = 0$:

$$\begin{bmatrix} -3 & 6 \\ 4 & -8 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-3w_1 + 6w_2 = 0$$

$$\vec{w} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\lambda = -11, \vec{v} = \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$\lambda = 0, \vec{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

General Solution To

$$x' = -3x + 6y$$

$$y' = 4x = 8y$$

$$\text{is } \mathbf{x} = C_1 e^{0t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_2 e^{-11t} \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$x = 2C_1 - 3C_2 e^{-11t}$$

$$y = C_1 + 4C_2 e^{-11t}$$

Particular Solution: (x_0, y_0) at $t = 0$

$$x_0 = 2C_1 - 3C_2$$

$$y_0 = C_1 + 4C_2$$

$$\begin{array}{l|l} 2C_1 - 3C_2 = x_0 & 8C_1 - 12C_2 = 4x_0 \\ -2C_1 - 8C_2 = -2y_0 & 3C_1 + 12C_2 = 3y_0 \\ \text{Add Equations} & \text{Add Equations} \\ -11C_2 = x_0 - 2y_0 & 11C_1 = 4x_0 + 3y_0 \end{array}$$

$$C_1 = \frac{4x_0 + 3y_0}{11}, C_2 = \frac{-x_0 + 2y_0}{11}$$

$$x = 2\left(\frac{4x_0 + 3y_0}{11}\right) - 3\left(\frac{-x_0 + 2y_0}{11}\right)e^{-11t}$$

$$y = \frac{4x_0 + 3y_0}{11} + 4\left(\frac{-x_0 + 2y_0}{11}\right)e^{-11t}$$

Next Time

Complex Eigenvalues

